## **Preliminary Design Review**

# MISCE project

Mechatronics for Improving and Standardizing Competences in Engineering



Competence: Automation Technology

Workgroup: University of Cagliari

University of Cassino and Southern Latio





This document is the Preliminary Design Review of the technical competence 'Automation Technology'. Its briefly contains the experimental platform analysed in MISCE project, to be designed and standardised for improving the acquisition level of this competence on engineering degrees.

Version: 2.0

Date: June 10th, 2025

Visit <a href="https://misceproject.eu/">https://misceproject.eu/</a> for more information.



$\mathbf{Inc}$	$\mathbf{O}\mathbf{V}$	$\circ$ t	-	ntc	ents
					41 II 🦠
		$\mathbf{O}$			,,,,,,

1 Cc	ompetence and skills	2
2 Ex	perimental proposals	3
2.1	Arduino R4 wifi	4
2.2	Peristaltic pumps	5
2.3	Relay module	5
2.4	LICHIFIT 130 Engines RC Boat Drive	6
2.5	TL-WA850RE Wireless Repeater	6
2.6	Sensor TDS Meter	7
2.7	Sensor PH Meter	7
2.8	Temperature and humidity sensor DHT11	8
2.9	CO2 concentration sensor CCS811	8
2.10	Water level sensor; Model n: ZP4510	9
2.11	Temperature sensor DS18B20	9
3 Cc	ompetence and skills analyses	10
Referer	nces	12
lodo	v of figures	
	ex of figures	
•	1. Arduino R4 Wi-Fi	
-	2. Peristaltic pumps	
Figure 4	4 LICHIFIT 130 Engines RC Boat Drive Set Engine Kit Shaft Propellers	6
-	5 TL-WA850RE Wireless Repeater	7
•	6 Sensor TDS Meter	
•	7 Sensor PH Meter	7
	7 Sensor PH Meter	7 8
Figure !	7 Sensor PH Meter	7 8 8
Figure	8 Temperature and humidity sensor DHT11 9 CO2 concentration sensor CCS811 10 Water level sensor; Model n: ZP4510	7 8 8 9
Figure	8 Temperature and humidity sensor DHT11	7 8 8 9
Figure :	8 Temperature and humidity sensor DHT11	7 8 8 9
Figure :	8 Temperature and humidity sensor DHT11 9 CO2 concentration sensor CCS811 10 Water level sensor; Model n: ZP4510	7 8 8 9
Figure Figure Inde	8 Temperature and humidity sensor DHT11	7 8 9 9
Figure Figure Inde Table I. Table II	8 Temperature and humidity sensor DHT11 9 CO2 concentration sensor CCS811 10 Water level sensor; Model n: ZP4510	7 8 9 9
Figure Figure Table II Table II	8 Temperature and humidity sensor DHT11	7 8 9 9 10



## 1 Competence and skills

The conceptual design presented in this document is referred to the technical competence:

C1. Automation Technology	

which related skills are (see Table I):

Table I. Skills of Automation Technology

S1.1.	To know the main electric/pneumatic and hydraulics elements						
S1.2.	To be able to design the functional behavior of the system						
S1.3.	To be able to understand the technical documentation of a						
	project/product						
S1.4.	To program the functional behavior of the device						
S1.5.	To debug the final planned behaviour of the system						

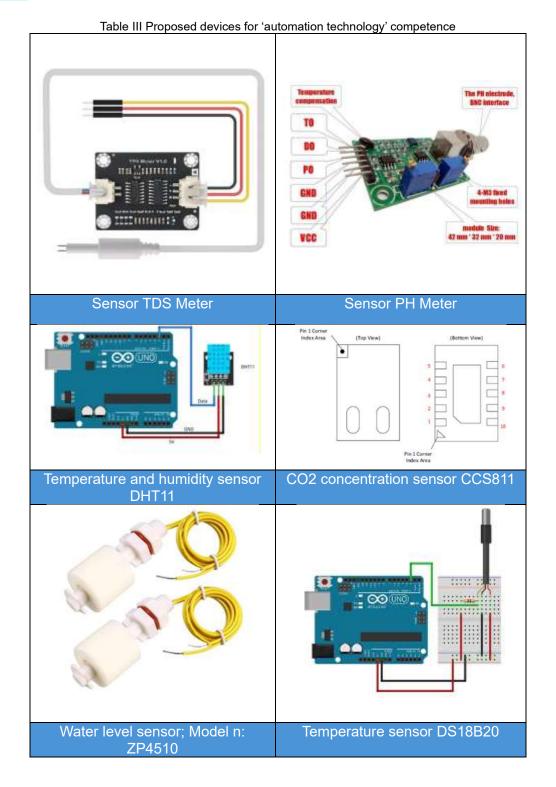
The different conceptual designs presented in this document have been analysed to ensure that can improve the acquisition level of the aforementioned competence.



## 2 Experimental proposals

For this competence, MISCE project proposes the joint use of the devices in Table II and III, together with their corresponding teaching materials.





In the following sections each device is detailed explained.

#### 2.1 Arduino R4 wifi

The aim of the experimental platform is to implement an automatic control system for hydroponic crops capable of actively monitoring and controlling the process. The system is implemented using low-cost sensors with the use of Arduino (see Figure 1) and actuators managed through the use of a PLC equipped with HMI interface. The system must be able to meet requirements such as reliability, user-friendliness and versatility. The aim is to create a system capable of reading as input data the desired values for the control of process variables and informing the human controller about



all process parameters, by printing the values of the process variables and displaying the status of the actuators on the HMI screen as well as storing the same data in files.

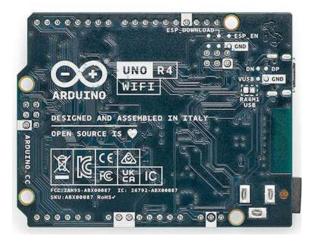


Figure 1. Arduino R4 Wi-Fi

The realization of the control system is based, of course, on the acquisition of data by sensors and on the ability to provide responses to the system through actuators. In the following sub-chapters will list these instruments.

#### 2.2 Peristaltic pumps

A circulation pump is required to push water into the ducts or pipes of irrigation of the plant, 3 precision pumps, peristaltic pumps, (see Figure 2) for nutrient dosage control and pH control.



Figure 2. Peristaltic pumps

### 2.3 Relay module

One-way relay modules for Arduino are used to connect the peristaltic pumps and the mixer (see Figure 3).





Figure 3. Relay module

These modules have a working voltage of 5 V, with an excitation current of about 70 mA in each direction, with the relay's LED status indicator.

#### 2.4 LICHIFIT 130 Engines RC Boat Drive

To mix the water has been installed a simple propeller shaft kit powered by motor DC (see Figure 4).



Figure 4 LICHIFIT 130 Engines RC Boat Drive Set Engine Kit Shaft Propellers

### 2.5 TL-WA850RE Wireless Repeater

The Arduino UNO R4 Wi-Fi board is internally equipped with the ESP32 Wi-Fi module with which it can communicate wirelessly. The PLC provides the possibility of communicating via Ethernet cable with the HMI, so the physical system requires a Wireless Access Point (see Figure 5) to allow Arduino and PLC to communicate.





Figure 5 TL-WA850RE Wireless Repeater

#### 2.6 Sensor TDS Meter

TDS (Total Dissolved Solids) indicates how many milligrams of soluble solids dissolved in a liter of water or particles per million (ppm). In general, the higher the TDS value, the more solid solubles are dissolved in water and less clean is the water (see Figure 6).

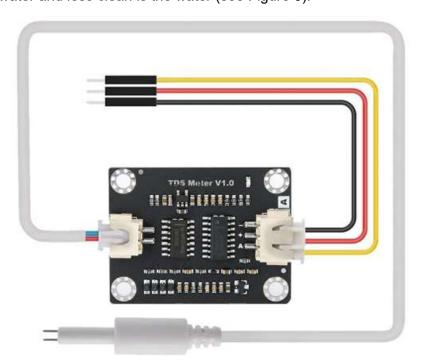


Figure 6 Sensor TDS Meter

#### 2.7 Sensor PH Meter

The sensor consists of a solder and a card which can be connected to each other via a BNC connector (see Figure 7).

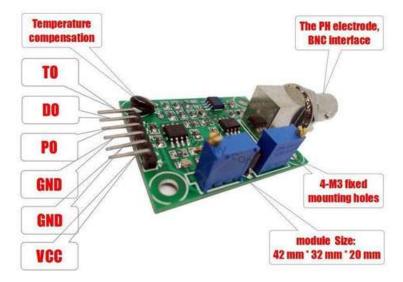


Figure 7 Sensor PH Meter

#### 2.8 Temperature and humidity sensor DHT11

The DHT11 (see Figure 8) module is a composite sensor combining a thermometer and a hygrometer in one body. The DHT11 module is the simplest and cheapest. The module measures humidity and temperature values and, through an 8-bit microcontroller enclosed in it, transforms them into digital signals.

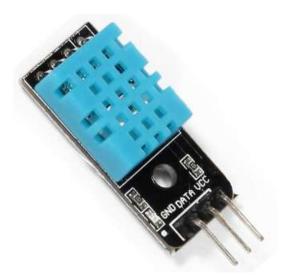


Figure 8 Temperature and humidity sensor DHT11

#### 2.9 CO2 concentration sensor CCS811

The CCS811 (see Figure 9) is an ultra-low power digital sensor designed for indoor air quality monitoring. Uses micro-hotplate technology to detect a wide range of volatile organic compounds (VOCs) in the air. The sensor integrates a microcontroller (MCU) with an analog-to-digital converter (ADC) and an I 2 C interface for communication. To measure the amount of CO2 equivalent (eCO2), the CCS811 uses intelligent algorithms to process sensor raw measurements and return a TVOC value or eCO2 levels.





Figure 9 CO2 concentration sensor CCS811

#### 2.10 Water level sensor; Model n: ZP4510

The ZP4510 (see Figure 10) water level sensor is a compact and reliable float switch, well-suited for monitoring liquid levels in various applications, from domestic tanks to industrial systems. Thanks to its simple installation and magnetic operating principle, it offers an effective solution for level detection in university projects.



Figure 10 Water level sensor; Model n: ZP4510

### 2.11 Temperature sensor DS18B20

This type of sensor (see Figure 11) is suitable for measuring the temperature of the environment, but also of soil or liquids thanks to the waterproof weld connected by rubber-coated cable. The DS18B20 is accurate enough to measure temperatures from -55°C to +125°C with an accuracy of 0.5°C and the integrated chip converts the analog signal into a digital signal from 9 to 12 bits (configurable).



Figure 11 Temperature sensor DS18B20

## 3 Competence and skills analyses

Table III summarises the competence and skills analyses of the proposed experimental platform attending to the contribution of acquisition of the technical competence 'automation technology' and their corresponding skills in Table I.





Table IV. Contribution of each proposed platform to automation technology competence and its corresponding skills

rable 19. Contribution of each proposed platform to automation technology competence and its corresponding skills						
Platform	S1.1	S1.2	S1.3	S1.4	S1.5	Overall competence contribution
Actuation of a single acting pneumatic cylinder	***	★★★☆☆	★★☆☆☆	★★☆☆☆	****	****
	Know the main electric/pneumatic and hydraulics elements	To be able to design the functional behaviour of the system.	Ability to understand the technical documentation of a project/product.	Ability to program the functional behaviour of the device	Capability to debug the final planned behaviour of the system	
Actuation of a double acting pneumatic cylinder		<b>★★★</b> ☆☆	<b>☆☆☆☆</b> ☆	***	<b>★★★★</b> ☆	3.6
	Know the main electric/pneumatic and hydraulics elements.	To be able to design the functional behaviour of the system.	Ability to understand the technical documentation of a project/product.	Ability to program the functional behaviour of the device	Capability to debug the final planned behaviour of the system.	
Movement-Phase" displacement	****	****	***	****	****	
	Know the main electric/pneumatic and hydraulics elements	To be able to design the functional behaviour of the system	Ability to understand the technical documentation of a project/product.	Ability to program the functional behaviour of the device	Capability to debug the final planned behaviour of the system	★★☆☆☆





### References

- [1] Marin, L., Vargas, H., Heradio, R., de La Torre, L., Diaz, J. M., & Dormido, S. (2020). Evidence-based control engineering education: Evaluating the LCSD simulation tool. IEEE Access, 8, 170183-170194.
- [2] Moreira, A. P., Costa, P., Gonçalves, J., & Faria, B. M. (2017). DC motor educational kit: a teaching aid in control theory. In CONTROLO 2016: Proceedings of the 12th Portuguese Conference on Automatic Control (pp. 879-889). Springer International Publishing.
- [3] Zhang, J., & Zhang, W. (2016). Design and Experiment Teaching Research Based on Brushless DC Motor Servo System. Education Research Frontier, 6(4).
- [4] Keshmiri, M., Jahromi, A. F., Mohebbi, A., Amoozgar, M. H., & Xie, W. F. (2012). Modeling and control of ball and beam system using model based and non model-based control approaches. International Journal on smart sensing and intelligent systems, 5(1), 14-35.
- [5] Hamed, B. (2010). Application of a LabVIEW for real-time control of ball and beam system. IACSIT International Journal of Engineering and Technology, 2(4), 401-407.
- [6] Israilov, S., Fu, L., Sánchez-Rodríguez, J., Fusco, F., Allibert, G., Raufaste, C., & Argentina, M. (2023). Reinforcement learning approach to control an inverted pendulum: A general framework for educational purposes. Plos one, 18(2), e0280071.
- [7] Boubaker, O. (2012, July). The inverted pendulum: A fundamental benchmark in control theory and robotics. In International conference on education and e-learning innovations (pp. 1-6). IEEE.
- [8] Iishiba, Y., Sugaya, J., & Yajima, K. (2015, October). The development of fundamental teaching materials and the inverted pendulum system as advanced sequence control. In 2015 7th International Conference on Information Technology and Electrical Engineering (ICITEE) (pp. 156-161). IEEE.
- [9] FOIT, K.; BANAŚ, W.; ĆWIKŁA, G. The pneumatic and electropneumatic systems in the context of 4th industrial revolution. In: *IOP Conference Series: Materials Science and Engineering*. IOP Publishing, 2018. p. 022024.
- [10] OLIVER, Mario Oscar Ordaz, et al. Design Algorithm For Sequential Pneumatic And Electropneumatic Systems. *International Journal of Combinatorial Optimization Problems and Informatics*, 2023, 14.3: 157.
- [11] Design of a Small-Scale Hydroponic System for Indoor Farming of Leafy Vegetables-Neiko V. Nikolov, Atanas Z. Atanasov, Boris I. Evstatiev , Valentin N. Vladut and Sorin-Stefan Biris <a href="https://doi.org/10.3390/agriculture13061191">https://doi.org/10.3390/agriculture13061191</a>
- [12] Automated Hydroponics System -Palash Agrawal1, Sankalp Bhagwate2, Dhruv Singhaniya3, Aditi Tamrakar4, Prof. Puja S. Agrawal5 1, 2, 3, 4Student, (Electronics and Communication Department, Shri Ramdeobaba College of Engineering and Management, Nagpur)5Assistant Professor, (Electronics and Communication Department, Shri Ramdeobaba College of Engineering and Management,Nagpur) <a href="https://doi.org/10.22214/ijraset.2023.49606">https://doi.org/10.22214/ijraset.2023.49606</a>
- [13] Optimal control of environmental conditions affecting lettuce plant growth in a controlled environment with artificial lighting: A review. Hesham A. Ahmed, Tong Yu-Xin, Yang Qi-Chang. <a href="https://doi.org/10.1016/j.sajb.2019.12.018">https://doi.org/10.1016/j.sajb.2019.12.018</a>
- [14] Sensore di Temperatura DS18B20 Datasheet (web pdf) e immagini dei collegamenti originali reperibili nel <a href="https://www.maffucci.it/2021/02/25/arduino-sensore-di-temperatura-digitale-ds18b20-utilizzo-in-modalita-singola/">https://www.maffucci.it/2021/02/25/arduino-sensore-di-temperatura-digitale-ds18b20-utilizzo-in-modalita-singola/</a>
- [15] TDS sensor Datasheet by Keystudio;



- [16] Immagini schemi Little Endian/Big Endian (Figure 122 e 123) reperibili su: <a href="https://www.instructables.com/ARDUINO-HACK-PLC-SIEMENS-THROUGH LANWIFI-INDUSTRIA/">https://www.instructables.com/ARDUINO-HACK-PLC-SIEMENS-THROUGH LANWIFI-INDUSTRIA/</a>
- [17] Web Server help, "AWP commands supported by the S7-1200 Web server" estratto gratuito e selezionato dall'utente della documentazione che Siemens ha messo a disposizione per questo prodottohttps://support.industry.siemens.com/